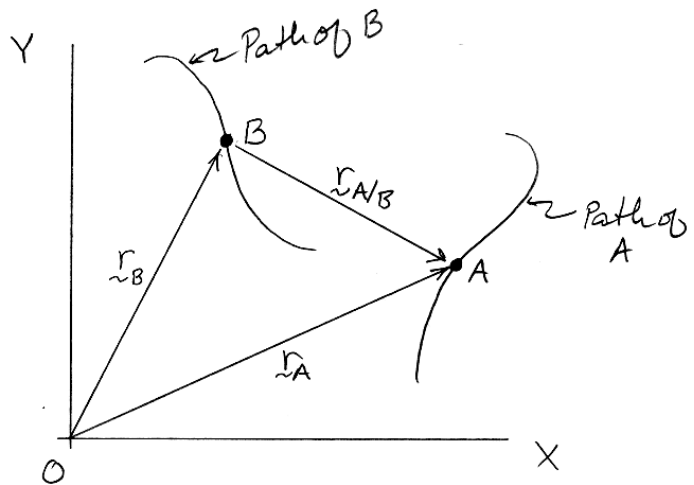


ME 2580 Dynamics

Relative Motion of Two Particles

The figure shows the paths of motion of two particles A and B . The vectors \underline{r}_A and \underline{r}_B represent the **position vectors** of A and B relative to a fixed point O , and the vector $\underline{r}_{A/B}$ represents the position vector of A **relative** to B . (Note that $\underline{r}_{A/B}$ starts at B and ends at A .)



Sometimes it is convenient to express the motion of a point relative to another moving point. For example, we can express the motion of point A relative to point B as follows: First, note that

$$\underline{r}_A = \underline{r}_B + \underline{r}_{A/B} \quad \text{or} \quad \underline{r}_{A/B} = \underline{r}_A - \underline{r}_B.$$

Then, we can **differentiate** this expression to define what we mean by the terms “**relative velocity**” and “**relative acceleration**.”

$$\underline{v}_{A/B} = \dot{\underline{r}}_{A/B} = \underline{v}_A - \underline{v}_B \quad \text{“relative velocity”}$$

$$\underline{a}_{A/B} = \ddot{\underline{r}}_{A/B} = \underline{a}_A - \underline{a}_B \quad \text{“relative acceleration”}$$

In words, the motion (velocity or acceleration) of A relative to B represents the motion of A as seen by an observer translating with B . This concept is used extensively in the analysis of rigid body kinematics.