

ME 2580 Example #45b: (Rigid Body Kinetics – Work and Energy Example #2)

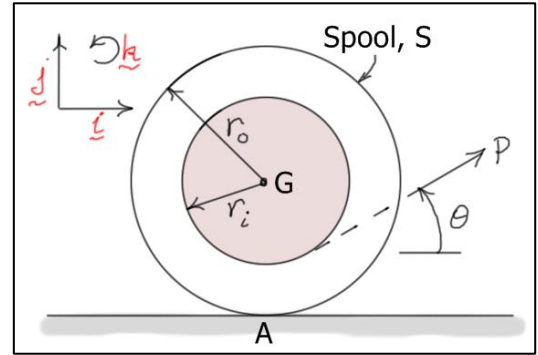
Given: $r_o = 0.4$ (m), $r_i = 0.25$ (m), $m = 100$ (kg)

$P = 200$ (N), $\theta = 20$ (deg), $k_G = 0.3$ (m)

Spool rolls without slipping; released from rest

Find: ω the angular velocity of S after G moves 2 (m) to the right.

Solution: (A is the instantaneous center (IC) of the spool)



$$\boxed{KE_1 + U_{1 \rightarrow 2} = KE_2} \quad (\text{initial state: 1, final state: 2})$$

with

$$\boxed{KE_1 = 0} \quad (\text{released from rest})$$

$$\boxed{KE_2 = \frac{1}{2} I_A \omega_2^2 = \frac{1}{2} (I_G + mr_o^2) \omega_2^2 = \frac{1}{2} (mk_G^2 + mr_o^2) \omega_2^2 = 12.5 \omega_2^2}$$

The spool **rolls without slipping**, so the only force that does work is P . The **distance** d_p over which P acts can be calculated as follows.

$$\boxed{d_p = \underbrace{\Delta x_G \cos(\theta)}_{\text{translation of S}} - \underbrace{r_i \Delta \theta}_{\text{rotation of S}} = 2 \cos(\theta) - r_i \left(\frac{\Delta x_G}{r_o} \right) = 2 \cos(20^\circ) - 0.25 \left(\frac{2}{0.4} \right) \approx 0.629385 \text{ (m)}}$$

Using this result, the **work done** by P can be calculated as follows.

$$\boxed{U_{1 \rightarrow 2} = P d_p \approx 200(0.629385) \approx 125.877 \text{ (N-m)}}$$

Substituting into the work-energy equation gives: $\omega_2 \approx \sqrt{\frac{125.877}{12.5}} \approx 3.17335 \approx 3.17 \text{ (rad/s)}$.

As the spool rolls to the **right**, the angular motion is **clock-wise**.

Note:

From an **earlier analysis** using **Newton's law**, the **angular acceleration** of the spool was calculated to be $\alpha \approx 1.00702 \text{ (rad/s}^2\text{)}$. Given a **constant angular acceleration**, the change in angular velocity can be calculated as follows.

$$\boxed{\omega_2^2 = \omega_1^2 + 2\alpha \Delta \theta = 2\alpha \left(\frac{\Delta x_G}{r_o} \right) \approx 2(1.00702) \left(\frac{2}{0.4} \right) \approx 3.17336 \approx 3.17 \text{ (rad/s)}}$$

Question:

It is **assumed** here that the spool **rolls without slipping**. How can this assumption be **verified**? Answer: Newton's law. See Example #43.