

## Elementary Engineering Mathematics

### Application of Trigonometric Functions in Mechanical Engineering: Part I

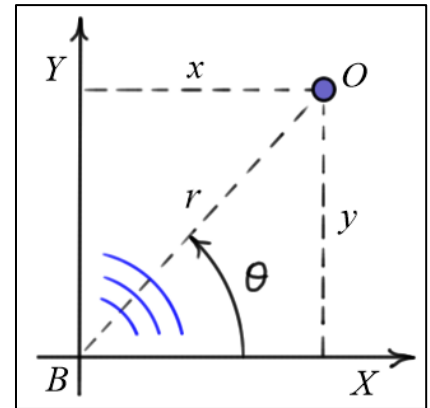
Given: The *position* of an object  $O$  is to be found relative to the base  $B$ . The distance  $r$  and the angle  $\theta$  were found using radar.

Find: Find the  $X$  and  $Y$  coordinates of the object  $O$ .

Solution: The distances  $x$  and  $y$  are related to  $r$  and  $\theta$  by the *trigonometric functions* defined for a *right triangle*. In particular,

$$\cos(\theta) = \frac{\text{adj}}{\text{hyp}} = \frac{x}{r}$$

$$\sin(\theta) = \frac{\text{opp}}{\text{hyp}} = \frac{y}{r}$$

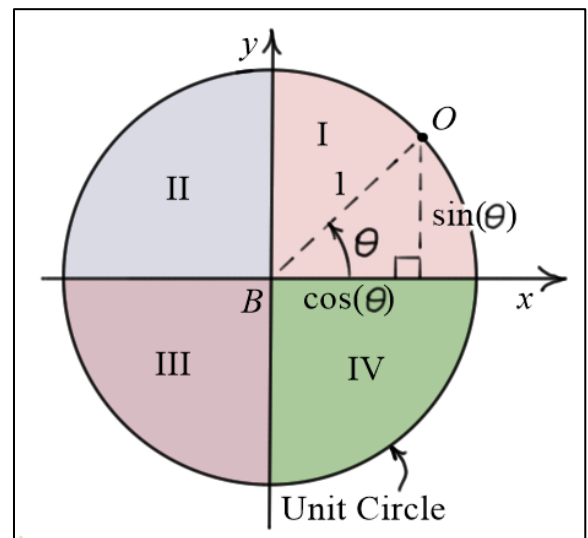


Note: The distance  $r$  and angle  $\theta$  are called the *polar coordinates* of  $O$ , and the distances  $x$  and  $y$  are called the *Cartesian coordinates* of  $O$ .

#### Sine and Cosine Functions:

These trigonometric functions may be defined based on lengths found within the *unit circle* (a circle of radius one). The triangle  $ABO$  is a right triangle with hypotenuse length  $r=1$  and sides of length  $x=\cos(\theta)$  and  $y=\sin(\theta)$ . Using the Pythagorean theorem, we see that the  $\sin(\theta)$  and  $\cos(\theta)$  are related to each other by the expression

$$\sin^2(\theta) + \cos^2(\theta) = 1 \quad (2)$$



Note also that due to the directions of the  $X$  and  $Y$  axes, these functions *change sign* as  $\theta$  is varied from  $0 \rightarrow \pm 360$  degrees (or  $0 \rightarrow \pm 2\pi$  radians). Table 1 summarizes how the  $\sin(\theta)$  and  $\cos(\theta)$  functions change as  $\theta$  is varied through each of the *four quadrants* (labeled as I, II, III, and IV in the diagram). Table 2 provides the values for some commonly used angles. A more detailed plot of the functions is shown below in Figure 1.

Quadrant	I	II	III	IV
$\sin(\theta)$	“+” ( $0 \rightarrow +1$ )	“+” ( $+1 \rightarrow 0$ )	“-” ( $0 \rightarrow -1$ )	“-” ( $-1 \rightarrow 0$ )
$\cos(\theta)$	“+” ( $+1 \rightarrow 0$ )	“-” ( $0 \rightarrow -1$ )	“-” ( $-1 \rightarrow 0$ )	“+” ( $0 \rightarrow +1$ )

Table 1. Variation of Sine and Cosine Functions Through the Quadrants

Angle, $\theta$	0	30 (deg) ( $\pi/6$ (rad))	45 (deg) ( $\pi/4$ (rad))	60 (deg) ( $\pi/3$ (rad))	90 (deg) ( $\pi/2$ (rad))
$\sin(\theta)$	0	$\frac{1}{2}$	$\frac{\sqrt{2}}{2}$	$\frac{\sqrt{3}}{2}$	1
$\cos(\theta)$	1	$\frac{\sqrt{3}}{2}$	$\frac{\sqrt{2}}{2}$	$\frac{1}{2}$	0

Table 2. Values for Commonly Used Angles

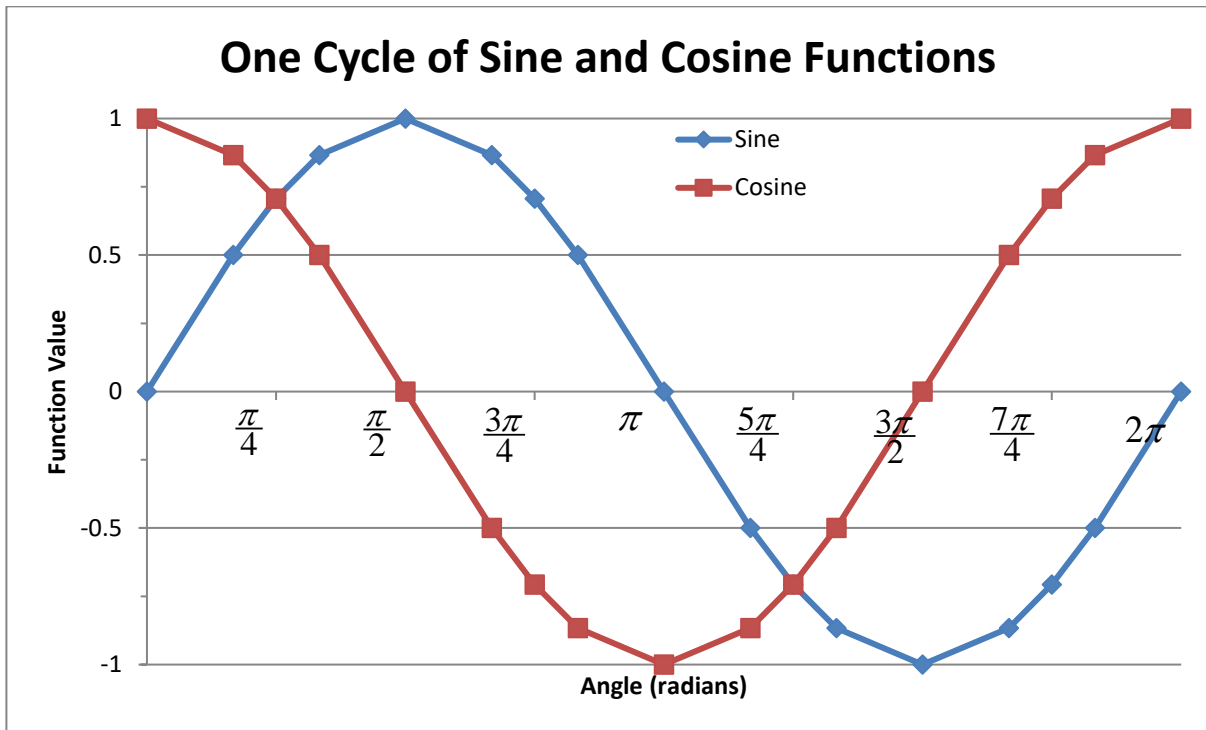


Figure 1. Plot of Sine and Cosine Functions

### Tangent Function:

Returning to object  $O$  in the first diagram, the distances  $x$  and  $y$  can be *related directly* using the *tangent* function

$$r = \frac{x}{\cos(\theta)} = \frac{y}{\sin(\theta)} \Rightarrow \boxed{\frac{y}{x} = \frac{\text{opp}}{\text{adj}} = \frac{\sin(\theta)}{\cos(\theta)} = \tan(\theta)} \quad \text{or} \quad \boxed{y = x \tan(\theta)} \quad (3)$$

Because the  $\tan(\theta)$  is a ratio of  $\sin(\theta)$  and  $\cos(\theta)$ , the *sign* of the tangent function is again determined by the *quadrant* of the angle. The results are summarized in Table 3. Note that  $\tan(\theta)$

is *undefined* when  $\cos(\theta) = 0$ , that is when  $\theta = \begin{cases} \pi / 2 \text{ (rad) (90 deg)} \\ 3\pi / 2 \text{ (rad) (270 deg)} \end{cases}$

Quadrant	I	II	III	IV
$\sin(\theta)$	“+” (0 → +1)	“+” (+1 → 0)	“-” (0 → -1)	“-” (-1 → 0)
$\cos(\theta)$	“+” (+1 → 0)	“-” (0 → -1)	“-” (-1 → 0)	“+” (0 → +1)
$\tan(\theta)$	“+” (0 → +∞)	“-” (-∞ → 0)	“+” (0 → +∞)	“-” (-∞ → 0)

Table 3. Variation of Sine, Cosine and Tangent Functions Through the Quadrants

### Other Trigonometric Functions:

It is also common to define the reciprocals of the sine, cosine and tangent functions. These are the *cosecant*, *secant*, and *cotangent* functions, respectively.

$$\boxed{\csc(\theta) = \frac{1}{\sin(\theta)}} \quad \boxed{\sec(\theta) = \frac{1}{\cos(\theta)}} \quad \boxed{\cot(\theta) = \frac{1}{\tan(\theta)}} \quad (4)$$

### Example 1:

Given: The polar coordinates of an object  $O$  are  $r = 3500$  (ft) and  $\theta = 150$  (deg).

Find: The Cartesian coordinates  $x$  and  $y$  of  $O$  using a) a calculator, and b) the values listed above for commonly used angles

### Solution:

a) Using a calculator to evaluate the sine and cosine functions:

$$\boxed{x = r \cos(\theta) = 3500 \times \cos(150) \approx -3031 \text{ (ft)}}$$

$$\boxed{y = r \sin(\theta) = 3500 \times \sin(150) = 1750 \text{ (ft)}}$$

b) Using the values for commonly used angles: Note first that  $150 = 180 - 30$  (deg), so

$$\sin(150) = \sin(30) = \frac{1}{2} \quad \text{and} \quad \cos(150) = -\cos(30) = -\frac{\sqrt{3}}{2}$$

$$\Rightarrow x = r \cos(\theta) = 3500 \times \frac{-\sqrt{3}}{2} \approx -3031 \text{ (ft)} \quad \text{and} \quad y = r \sin(\theta) = 3500 \times \frac{1}{2} = 1750 \text{ (ft)}$$

### Inverse Trigonometric Functions:

Given values for the distances  $x$ ,  $y$ , and/or  $r$ , the angle  $\theta$  can be found using *inverse trigonometric functions* as follows:

$$\theta = \sin^{-1}(y/r) = \cos^{-1}(x/r) = \tan^{-1}(y/x)$$

### Example 2:

Given: The Cartesian coordinates of an object  $O$  are  $x = -3250$  (ft) and  $y = 1250$  (ft).

Find: a) the distance  $r$ , and b) the angle  $\theta$ .

Solution:

a) Distance  $r$  is found by using the Pythagorean theorem:

$$r = \sqrt{(-3250)^2 + 1250^2} \approx 3482 \text{ (ft)}$$

b) The angle can be found using the inverse tangent function, being careful to *identify* the *correct quadrant* based on the signs of  $x$  and  $y$ .

$$\theta = \tan^{-1}\left(\frac{+1250}{-3250}\right) \approx 159 \text{ (deg)} \quad \text{or} \quad \theta = \tan^{-1}\left(\frac{+1250}{-3250}\right) \approx 2.77 \text{ (rad)}$$

Your *calculator* will probably always give you an angle that is between  $-\pi/2$  and  $-\pi/2$  radians, so you will have to *adjust* the result by adding  $\pi$  (rad) or 180 (deg). Some may have an “atan2” function that determines the quadrant by individually considering the sign of the numerator and denominator of the ratio.