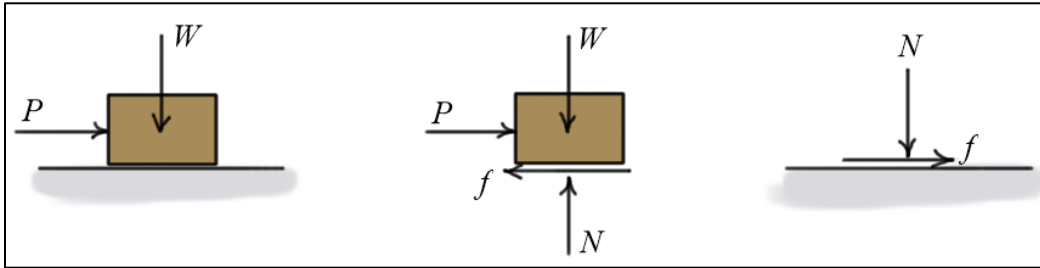


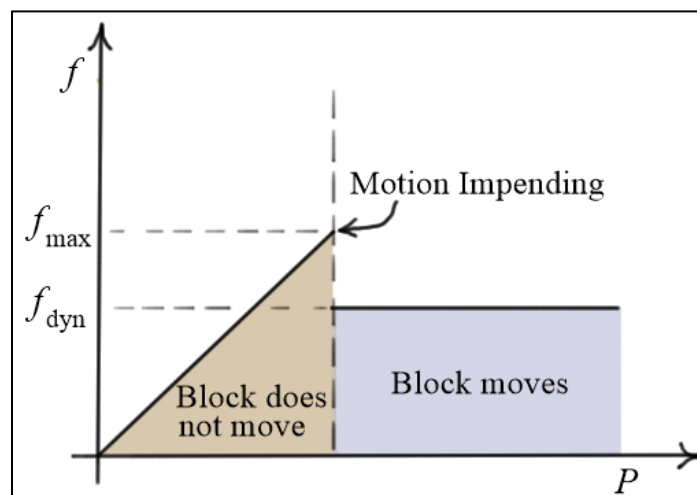
Elementary Statics

Dry Friction

- When two bodies are in *contact*, the *reactive contact force* can be broken into *two components*, one *normal* and one *tangent* to the plane of contact.
- The component of the contact force *tangent* to the plane of contact is called the *friction force* (f), and it is the result of the *relative roughness* of the contacting surfaces.
- Consider a *block* resting on a *horizontal plane* with an *applied force* P .



- Depending on the *magnitude* of P and the *roughness* of the contacting surfaces, the block *may* or *may not* move.
- There are *three* distinct *possibilities* in this case.
 - the block *slides*
 - the block *does not slide*, even when P is increased slightly
 - the block *does not slide*, but it does slide when P is increased slightly
- In the last case, *motion* is *impending*, because if P is increased slightly, the block will move.
- One *model* of *friction* is described by the plot below. As P is *increased* from zero, the friction force *matches it* up to a limiting value of f_{\max} . As P is *increased beyond this value*, the *friction force drops* to its dynamic value f_{dyn} which is *approximately constant*.



- The values of f_{\max} and f_{dyn} are given in terms of the **normal force** N and the **coefficients** of **static** and **kinetic friction**.

$$\boxed{f_{\max} = \mu_s N} \quad \mu_s \text{ is the } \textit{coefficient} \text{ of } \textit{static friction}$$

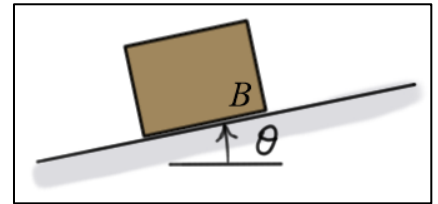
$$\boxed{f_{\text{dyn}} = \mu_k N} \quad \mu_k \text{ is the } \textit{coefficient} \text{ of } \textit{kinetic friction}$$

- The **coefficients** of **friction** (μ_s and μ_k) depend on the **relative roughness** of the two surfaces. See your textbook or other reference sources for some **typical values**.

Example #1:

Given: Weight, W and coefficient of static friction μ_s .

Find: Maximum angle θ for which block B will remain in equilibrium.



Solution:

For this limiting case, we assume that motion is impending down the plane ($f = \mu_s N$) and write the equilibrium equations.

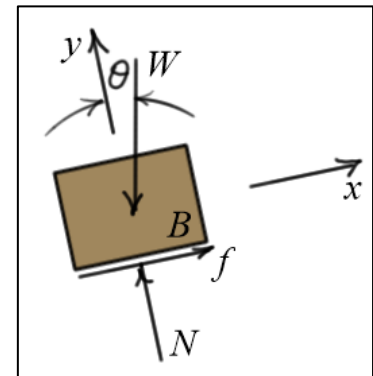
$$+\nearrow \sum F_y = N - W \cos(\theta) = 0 \Rightarrow \boxed{N = W \cos(\theta)}$$

$$+\searrow \sum F_x = f - W \sin(\theta) = 0 \Rightarrow \boxed{\mu_s N - W \sin(\theta) = 0}$$

Combining the two boxed equations gives

$$\mu_s W \cos(\theta) - W \sin(\theta) = 0 \Rightarrow \boxed{\theta = \tan^{-1}(\mu_s)}$$

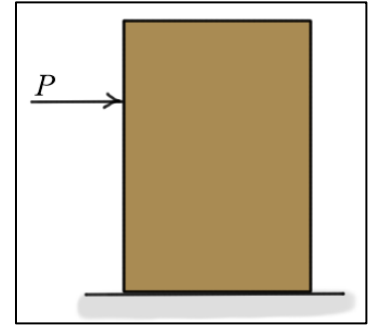
Specific case: If $\boxed{\mu_s = 0.4}$, then $\boxed{\theta = \tan^{-1}(0.4) \approx 21.8 \text{ (deg)}}$.



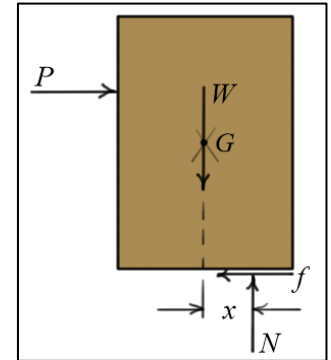
- If $\boxed{\theta < 21.8 \text{ (deg)}}$, the block will not move and $\boxed{f < f_{\max} = \mu_s N}$
- If $\boxed{\theta = 21.8 \text{ (deg)}}$, the block will not move and $\boxed{f = f_{\max} = \mu_s N}$ (motion impending)
- If $\boxed{\theta > 21.8 \text{ (deg)}}$, the block will slide down the plane and $\boxed{f = f_{\text{dyn}} = \mu_k N}$

Tipping Problems

- Consider the box resting on a plane with *horizontal force* $P = 0$. If the *weight* within the box is *evenly distributed*, the *normal force* exerted by the ground on the box is *uniformly distributed along the bottom* of the box.



- As the value of P is increased ($P > 0$), the *normal distributed force* exerted by the ground on the box is *skewed* either *to the right* or *to the left* of center.
- If the box is in *static equilibrium* ($P = f$), the *normal force* will always be *skewed* to the *right of center*.



- If P is *above* the *mass center* G , both P and f will have *clockwise moments* about G which will be *balanced* by a *counterclockwise moment* from N .
- If P is *below* the *mass center* and above the bottom of the box, P will have a *counterclockwise moment* about G , and f will have a *larger clockwise moment* about G . This *net clockwise moment* will be balanced by a *counterclockwise moment* of N . (Note: The friction force f has a *larger moment arm* about G than does P .)
- If the box is *not* in *static equilibrium* ($P > f$), the *normal force* will be *skewed to the right of center* if P is *above* G , and it *can* be *skewed left* or *right of center* if P is *below* G , depending on the relative magnitudes of P and f .
- Consider the case of static equilibrium where the *applied force* P is *above* the mass center, and the *resultant normal force* (N) is to the *right of center* as shown in the free-body diagram.
- In this case, the moments of the *applied force* P and the *friction force* f will both have a *tendency* to *tip* the box to the right, and the moment of *normal force* N will *counter* that.
- If N acts at the *edge of the box* to counter the effects of P and f , the box will be on the *verge* of *tipping*.
- If N needs to act beyond the *edge of the box* to counter P and f , the box will *tip*.

Example #2:

Given: 30 (kg) crate loaded as shown with $\mu_s = 0.35$

Find: a) tension T required to move the crate
b) whether the crate slides or tips

Solution:

a) To find the minimum tension required to move the crate, assume motion is impending and $f = \mu_s N = 0.35N$.

Force equations:

$$\rightarrow \sum F_x = f - T \cos(30) = 0$$

$$+\uparrow \sum F_y = N + T \sin(30) - mg = 0$$

Simultaneous equations:

$$\begin{aligned} 0.35N - (\cos(30))T &= 0 \\ N + (\sin(30))T &= 30(9.81) \end{aligned}$$

Solving gives:

$$\begin{aligned} N &\approx 244.827 \approx 245 \text{ (N)} \\ T &\approx 98.9457 \approx 98.9 \text{ (N)} \end{aligned}$$

Moment equation:

$$\begin{aligned} \odot \sum M_A &= (0.45)mg + 0.6f - (0.45 + x)N = 0 \\ \Rightarrow (0.45 + x)N &= (0.45)mg + 0.6(0.35)N \\ \Rightarrow x &= \frac{(0.45)mg}{N} + 0.6(0.35) - 0.45 \\ \Rightarrow x &\approx 0.3009 \approx 0.301 \text{ (m)} \end{aligned}$$

b) The crate will *slide* (and not tip) because when motion is impending, N is found to be located between the centerline and edge of the crate, that is, $x \approx 0.301 \text{ (m)} \leq 0.45 \text{ (m)}$. **Note:** If x was found to be greater than 0.45 when motion is impending, the crate would tip and not slip.

