

Intermediate Dynamics

Introduction to Lagrangian Dynamics

Newton/Euler Equations of Motion

One approach to finding the *equations of motion* (EOM) of a mechanical system is to use the *Newton/Euler* equations of motion.

$$\begin{aligned} \sum_i \underline{F}_i &= m {}^R \underline{a}_G \\ \sum_i (\underline{M}_G)_i &= (\underline{I}_G \cdot {}^R \underline{\alpha}_B) + ({}^R \underline{\omega}_B \times \underline{H}_G) \end{aligned}$$

or

$$\sum_i (\underline{M}_A)_i = (\underline{I}_G \cdot {}^R \underline{\alpha}_B) + ({}^R \underline{\omega}_B \times \underline{H}_G) + (\underline{r}_{G/A} \times m {}^R \underline{a}_G)$$

Here, G is the *mass center* of the body and A is *any point*. In this approach, *bodies are isolated* one-by-one using *free body diagrams*. Then the above equations are used to write the EOM. As a result, these equations contain *unknown constraint forces* and *moments*. Hence, the differential equations of motion contain algebraic unknowns. Equations of this form are often referred to as *differential/algebraic equations* of motion.

Lagrange's Equations of Motion

The application of *Lagrange's equations of motion* differs from the application of the Newton/Euler equations in the following ways:

- Focus is on the *entire system* rather than individual components.
- EOM are formulated in terms of the *scalar functions* of *work* and *kinetic energy*.
- *Constraint forces* and *moments* that do *no work* are *eliminated* from the analysis.

For many systems the resulting equations of motion form a set of *differential* equations. For more complex systems they form a set of *differential/algebraic* equations. The specific form of Lagrange's equations is presented in later notes.

Note:

Lagrange's equations are not the only *system-based* formulation of EOM. Other system-based formulations include *d'Alembert's Principle* and *Kane's Equations*.