

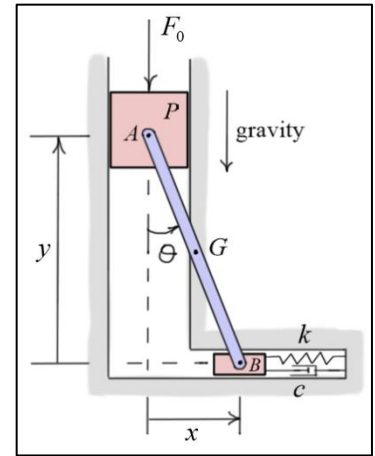
Intermediate Dynamics

Exercises #10

1) Find the equilibrium positions of the system of Exercises #8, problem #1.

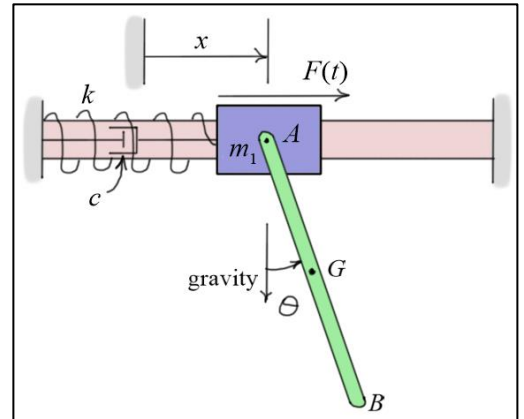
Use the following data.

$$\begin{aligned}
 mg &= 4 \text{ lb} & \ell &= 2 \text{ ft} \\
 m_p g &= 3 \text{ lb} & k &= 17.68 \text{ lb/ft} \quad (\ell \text{ is the length of } AB) \\
 F_0 &= 20 \text{ lb}
 \end{aligned}$$

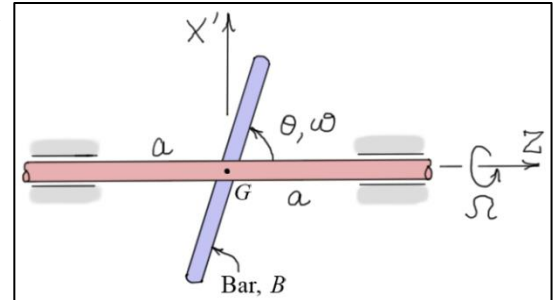


2) Show that $x = \theta = 0$ is an equilibrium position for the system of Exercises #8, problem #2. Linearize the equations of motion about this position and calculate the natural frequencies and mode shapes of the system using the following physical data. Describe the motion of each mode.

$$\begin{aligned}
 m_1 g &= 10 \text{ lb} & \ell &= 2 \text{ ft} \\
 m_2 g &= 5 \text{ lb} & k &= 300 \text{ lb/ft} \quad (\ell \text{ is the length of } AB)
 \end{aligned}$$



3) Given that $M_\theta = 0$ and $\dot{\phi} = \Omega = \text{constant}$, find the equilibrium positions for the angle θ for the bar of Exercises #8, problem #3. Then linearize the equation of motion about these positions. Determine the stability of small motions about each of these positions. Find the torque M_ϕ required so that $\dot{\phi} = \Omega = \text{constant}$.



4) Given that $M_\theta = 0$, $\dot{\phi} = \Omega = \text{constant}$, and $b = 0$, show that the equilibrium position for the angle θ for the bar of Exercises #8, problem #4 is approximately $\theta_{eq} \approx 58.7$ (deg). Then linearize the equation of motion about this position and determine the stability of small motions about that position. Find the torque M_ϕ required so that $\dot{\phi} = \Omega = \text{constant}$. Use the following physical data:

$$\begin{aligned}
 mg &= 5 \text{ lb} & k &= 10 \text{ ft-lb/rad} \\
 \ell &= 2 \text{ ft} & \Omega &= 4\pi \text{ rad/s} \\
 c &= 0
 \end{aligned}$$

